

Sysmac Library for NJ/NX/NY Controller

SYSMAC-XR014

Dimension Measurement Library



✓ Measure thickness, flatness, level difference, and other dimensions using displacement sensors.

Issue 1 There is no knowledge what arithmetic expression should be used.

Issue 2 The more sensors are used, the more complicated and time consuming the program will be.

Dimension Measurement Library offers solution!

The Function Blocks in this library can be used to easily calculate the dimensions required for your application from the values obtained from displacement sensors. Programming time can be reduced significantly. For example, previously the ST program for measuring level differences while moving sensor required 2,650 steps, but now, thanks to Function Blocks, it requires only 325 steps.

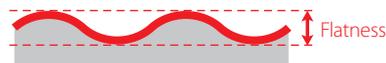
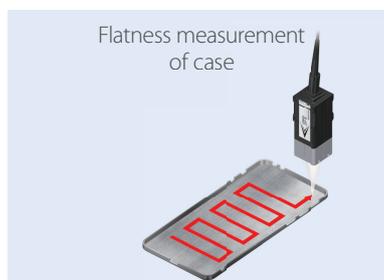
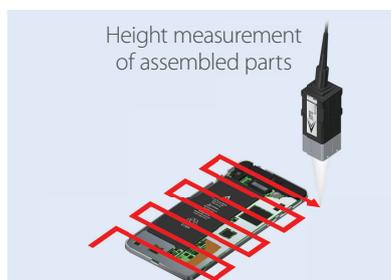
Program size reduced by
up to 85%*

* Omron survey as of October 2016

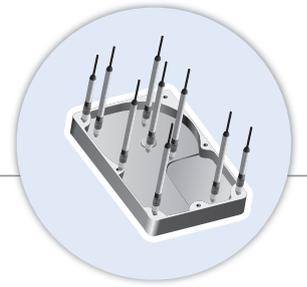
Multipoint Measurement



2D Shape Measurement

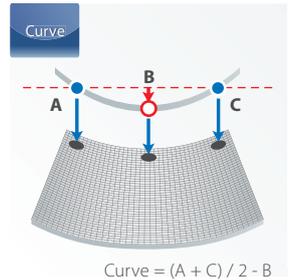
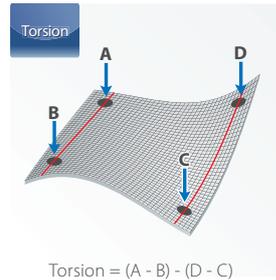
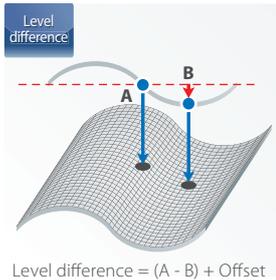
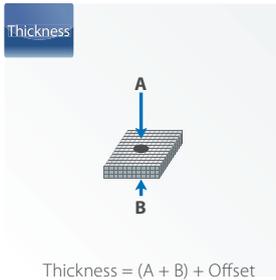
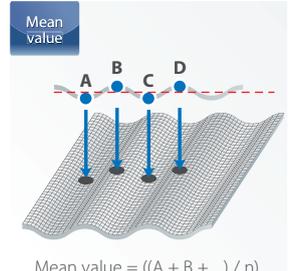
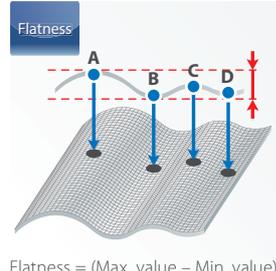
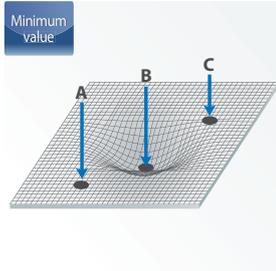
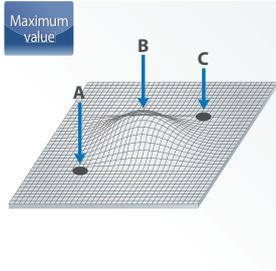


Function Blocks in this library can be used to calculate dimensions from measurement values obtained from two or more sensors.



Reduced work : No program required for calculation

To calculate the required dimension, just select the Function Block that is fit for your purpose, and then specify sensors for parameters.



Thickness = (A + B) + Offset

Level difference = (A - B) + Offset

Flatness = (Max. value - Min. value)

Mean value = ((A + B + ...) / n)

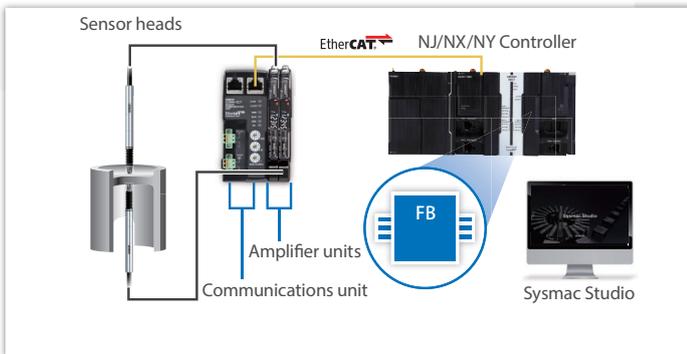
Torsion = (A - B) - (D - C)

Curve = (A + C) / 2 - B

System Configurations

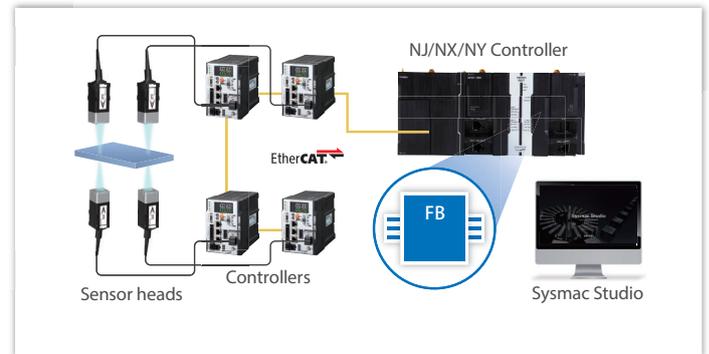
E9NC for contact sensing

System configuration



ZW-8000/7000/5000 for non-contact sensing

System configuration



Compatible Models

| Name | Model |
|---|-----------------|
| Machine Automation Controller NJ/NX CPU Unit | NX701-1□□□ |
| | NJ101-□□□□ |
| | NJ501-□□□□ |
| | NJ301-□□□□ |
| | NX1P2-□□□□□□(1) |
| NX102-□□□□ | |
| Industrial PC Platform NY IPC Machine Controller | NY5□□-1 |
| | NY5□□-5 |
| Automation Software Sysmac Studio | SYSMAC-SE2□□□ |
| Sensor Head | E9NC-TH□□□□ 2M |
| Amplifier Unit | E9NC-TA0 |
| Sensor Communications Unit (EtherCAT) | E3NW-ECT |

Compatible Models

| Name | Model |
|---|----------------------|
| Machine Automation Controller NJ/NX CPU Unit | NX701-1□□□ |
| | NJ101-□□□□ |
| | NJ501-□□□□ |
| | NJ301-□□□□ |
| | NX1P2-□□□□□□(1) |
| NX102-□□□□ | |
| Industrial PC Platform NY IPC Machine Controller | NY5□□-1 |
| | NY5□□-5 |
| Automation Software Sysmac Studio | SYSMAC-SE2□□□ |
| Sensor Head | ZW-80□□/70□□/50□□ M |
| Controller | ZW-8000□/7000□/5000□ |

Note. Refer to "Sysmac Library Catalog (P102)" for applicable version.

The Function Blocks can be used to measure while moving a sensor and calculate dimensions. Shape can be measured easily by linking movement data (X/Y) of the stage or robot with measurement data (Z) from the sensor in the controller, without any complicated programming.

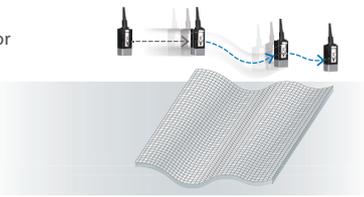


Reduced work : Function Blocks prevent the out of measurement range error

Function Blocks can adjust the height of the sensor to keep the measured surface height within the measurement range of the sensor even when the surface height varies greatly. You can select from the following two control methods to suit your application.

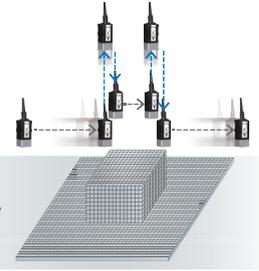
Tracer Control

This method is suitable for measuring shapes whose height varies gradually.



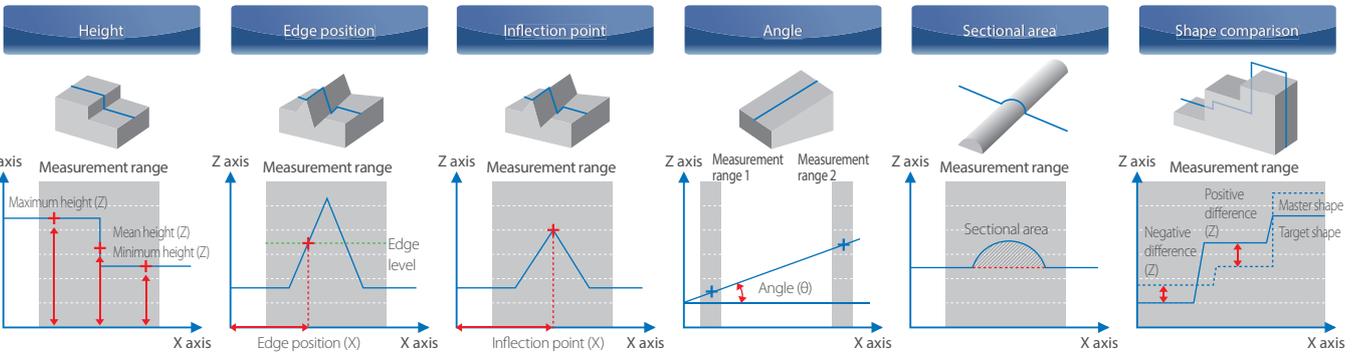
Surface Search

This method is suitable for measuring shapes whose height varies greatly and sharply. When the height of the measurement surface changes and it goes outside the measurement range of the displacement sensor, the height of the displacement sensor is readjusted and the measurement is continued.



Reduced work : Function Blocks easily create 2D shape data

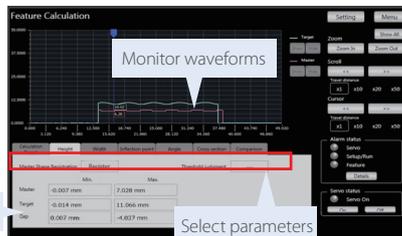
2D shape data can easily be created from moving measurement data to calculate the dimension of the characteristic point. To calculate the required dimension, just select the Function Block that is fit for your purpose, and then specify the measurement range.



Reduced work :

No need to design screens for setting and measurement

Omron provides HMI templates that include functionality for various applications as well as basic setting(sensor and servo system).



Set parameters

Select parameters

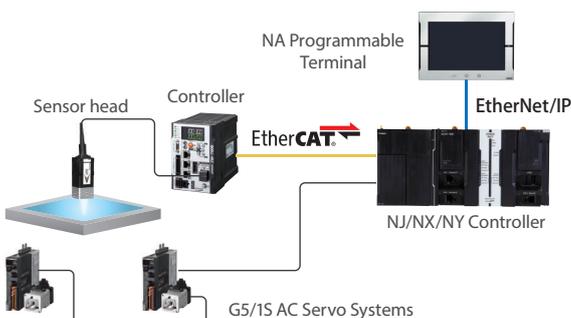
Built-in functions:

Waveform display of line measurement data, characteristic point calculation, comparison calculation, etc.

* Ask your Omron sales representative for details.

System Configuration

ZW-8000/7000/5000
for non-contact sensing



Compatible Models

| Name | Model |
|---|--------------------------|
| Machine Automation Controller NJ/NX CPU Unit | NX701-1□□□ |
| | NJ101-1□□□ * |
| | NJ501-□□□□ |
| | NJ301-□□□□ |
| | NX1P2-□□□□□□(1) |
| Industrial PC Platform NY IPC Machine Controller | NY5□□-1 |
| | NY5□□-5 |
| Automation Software Sysmac Studio | SYSMAC-SE2□□□□ |
| Sensor Head | ZW-80□□0/70□□0/50□□0 □□M |
| Controller | ZW-8000□/7000□/5000□ |
| Programmable Terminal | NA5-□□W |
| AC Servo Drive | R88D-KN□-ECT |
| | R88D-1SN□-ECT |

* This Library is not available for NJ101-90□□ CPU Units.

Note. Refer to "Sysmac Library Catalog (P102)" for applicable version.

Function Block (FB) Specifications

Multipoint Measurement

| Name | FB name | Description |
|--|------------------------|--|
| Point Measurement Calculation (Maximum Value, Minimum Value, Flatness and Mean Value) | CalcPointMeasurement | Utilizes the measurement data obtained from 1 to 16 measurement sensors to perform the calculation of maximum value, minimum value, flatness, and mean value. |
| Deviation Calculation | PointMeasure_Deviation | Outputs the difference of measurement values (Input1 and Input2) obtained from two measurement sensors on the calculation result. |
| Torsion Calculation | PointMeasure_Torsion | Calculates the degree of torsion from the measurement values (Input1, Input2, Input3, and Input4) obtained from four measurement sensors and outputs it on the calculation result. |
| Curve Calculation | PointMeasure_Curve | Calculates the degree of curve from the measurement values (Input1, Input2, and Input3) obtained from three measurement sensors and outputs it on the calculation result. |
| Thickness Calculation | PointMeasure_Thickness | Calculates the thickness from the measurement values (Input1 and Input2) obtained from two measurement sensors and outputs it on the calculation result. |

2D Shape Measurement

| Name | FB name | Description |
|--|-----------------------------------|---|
| Line Measurement with Cartesian Coordinate System (Surface Search/Tracer Control) | LineMeasure_Cartesian | Measures the height of measurement surfaces while moving a single axis with a displacement sensor in X and Z directions. From the measurement result, this Function Block creates the line measurement data. You can select from the following two methods to control the single axis during measurement: Surface Search and Tracer Control. |
| Line Measurement with Cartesian Coordinate System 2 (Surface Search/Tracer Control) | LineMeasure_Cartesian2 | |
| Master 2D Shape Data Creation | LineMeasure_CreateShape2D_Master | Converts from the line measurement data to the 2D shape data and registers it as master data. |
| Master 2D Shape Data Creation 2 | LineMeasure_CreateShape2D_Master2 | |
| 2D Shape Data Creation | LineMeasure_CreateShape2D | Converts from the line measurement data to the 2D shape data. Correction is performed so that the target data has the same slope, height and position as the master 2D shape data. |
| 2D Shape Data Creation 2 | LineMeasure_CreateShape2D2 | |
| 2D Shape Height Measurement | Shape2D_Height | Measures heights in a specified measurement range of the 2D shape data. |
| 2D Shape Height Measurement 2 | Shape2D_Height2 | |
| 2D Shape Edge Position Measurement | Shape2D_Edge | Measures the position (X coordinate) at which a height in the specified measurement range of the 2D shape data passes the edge level. |
| 2D Shape Edge Position Measurement 2 | Shape2D_Edge2 | |
| 2D Shape Inflection Point Measurement | Shape2D_InflexionPoint | Measures the position at which the shape line is bent (inflection point) in the specified measurement range of the 2D shape data. If there are multiple inflection points in the measurement range, the position (inflection point) with the largest amount (sensitivity) of bend is output. |
| 2D Shape Inflection Point Measurement 2 | Shape2D_InflexionPoint2 | |
| 2D Shape Angle Measurement | Shape2D_Angle | Draws a straight line between heights within in the two calculation measurement ranges of the 2D shape data. Then, the Function Block calculates the angle θ of the straight line to the horizontal surface. This Function Block also outputs slope a and intercept b of the straight line relative to the horizontal axis X and vertical axis Z (height). |
| 2D Shape Angle Measurement 2 | Shape2D_Angle2 | |
| 2D Shape Sectional Area Measurement | Shape2D_Area | Calculates the area in the specified integral range of the 2D shape data. |
| 2D Shape Sectional Area Measurement 2 | Shape2D_Area2 | |
| 2D Shape Comparison Measurement | Shape2D_Compare | Compares the master 2D shape data and target 2D shape data in the specified measurement range and detects the difference in height (Z direction). |
| 2D Shape Comparison Measurement 2 | Shape2D_Compare2 | |

Note. A function block or function that the last number of its name is "2", supports a variable-length array. It is available for unit version 1.18 or later.

Common (ZW Operation Control)

| Name | FB name | Description |
|-----------------------|---------------------|--|
| ZW Zero Reset Control | ZW_ZeroResetControl | Performs the Zero Reset and Clear Zero Reset functions for the specified task of the ZW-8000/7000/5000 Confocal Fiber Displacement Sensor through EtherCAT communications. |
| ZW Command Control | ZW_CmdControl | Controls the commands for the ZW-8000/7000/5000 Confocal Fiber Displacement Sensor that communicates with the NJ/NX/NY Controller via EtherCAT. |

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Note: Do not use this document to operate the Unit.

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