

SX (400V)

High performance Vector Control

- IP54 full range.
- Compact design & Robustness
- Built-in Filter according to C3 Class
- Built-in Fuses (From 200 kW)
- Safety according EN13849-1 and EN62061 standards
- Load curve control
- HCB technology (Half controlling Bridge)
- Logic programmability
- Pre-maintenance alarms
- Options flexibility (I/O's, Fieldbus, PTC/PT100, Multiple Pump control, Encoder, Crane control)
- Communications options (Modbus, Dnet, Profibus)
- 24 VDC control board supply
- Liquid cooling drive version
- 12-pulse rectifier option.
- Flexible cable connections & User Friendly wiring connection
- CE, UL, RoHS, DNV

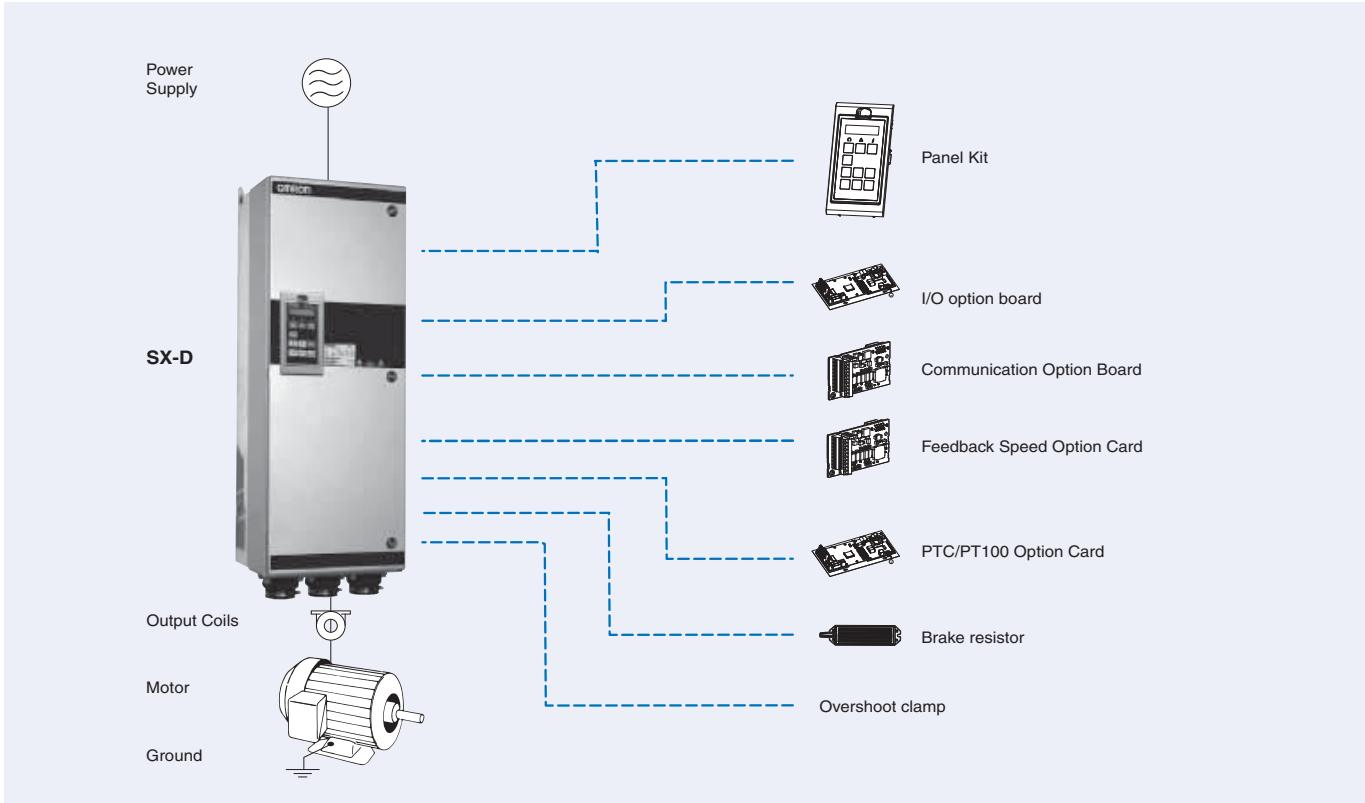
Ratings

- 400 V Class three-phase 0.75 to 800 kW



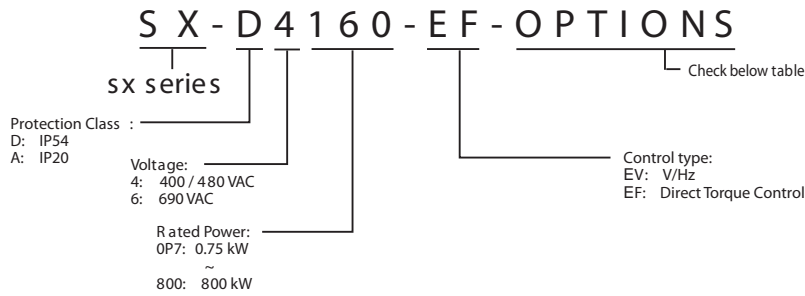
Frequency Inverters

System configuration



Specifications

Type designation



Options available

| Options | Letter ("?" means no character) | Options | Letter ("?" means no character) |
|-------------------------|---|----------------------------------|--|
| Control panel | "?" = Standard control panel (Std.PPU) "A" = Blank control panel (Blank PPU) | Option board position 3 | "?" = No option "I" = Encoder "J" = PTC/PT100 "K" = Extended I/O" |
| Built-in EMC filter | "?" = Standard EMC inside (Category C3) "B" = IT-Net (filter disconnected from ground) | Option board Fieldbus position 4 | "?" = No option "L" = DeviceNet "M" = Profibus-DP "N" = RS232/485 "O" = EtherNet Modbus TCP |
| Built-in brake chopper | "?" = No brake chopper or DC-connection included "C" = Brake chopper & DC-connection included "D" = Only DC-connection included | Liquid Cooling | "?" = No Liquid Cooling "P" = Liquid Cooling |
| Standby power supply | "?" = Not included "E" = Standby power supply included | Standard | "?" = IEC "Q" = UL |
| Safe stop | "?" = Not included "F" = Safe stop included | Marine | "?" = No marine option "R" = Marine option included |
| Coated boards | "?" = No coating "G" = Coated boards | Cabinet input options | "?" = No cabinet input options "S" = Main switch included "T" = Main contactor included "U" = Main switch + contactor included |
| Option board position 1 | "?" = No option "H" = Crane I/O "I" = Encoder "J" = PTC/PT100 "K" = Extended I/O" | Cabinet output options | "?" = No cabinet output options included "V" = dV/dt filter included "W" = dV/dt filter + Overshoot clamp included "X" = Sinusfilter included |
| Option board position 2 | "?" = No option "I" = Encoder "J" = PTC/PT100 "K" = Extended I/O" | additional options | "Z1" = Common mode output filter "Z2" = Cable gland kit "Z3" = Motor PTC connection Only models from 0.37 to 37KW |

400 V class

| Three-phase: SX-□4□□□-E□ | | 0P7 | 1P5 | 2P2 | 3P0 | 4P0 | 5P5 | 7P5 | 011 | 015 | 018 | 022 | 030 | 037 | 045 | 055 | |
|---------------------------|-----------------------------------|-----------------------------|-----|-----|------|------|------|------|------|------|------|------|------|------|------|------|--|
| Motor kW ¹ | For HD setting | 0.55 | 1.1 | 1.5 | 2.2 | 3 | 4 | 5.5 | 7.5 | 11 | 15 | 18.5 | 22 | 30 | 37 | 45 | |
| | For ND setting | 0.75 | 1.5 | 2.2 | 3 | 4 | 5.5 | 7.5 | 11 | 15 | 18.5 | 22 | 30 | 37 | 45 | 55 | |
| Output characteristics | Max output current (A) □-EF | 3.8 | 6.0 | 9.0 | 11.3 | 14.3 | 19.5 | 27.0 | 39.0 | 46.0 | 55.0 | 69.0 | 92.0 | 111 | 108 | 131 | |
| | Max output current (A) □-EV | 3.0 | 4.8 | 7.2 | 9.0 | 11.4 | 15.6 | 21.6 | 31.0 | 37.0 | 44.0 | 55.0 | 73.0 | 89.0 | 108 | 131 | |
| | Rated output current (A) at HD | 2.0 | 3.2 | 4.8 | 6.0 | 7.6 | 10.4 | 14.4 | 21.0 | 25.0 | 29.6 | 37.0 | 49.0 | 59.0 | 72.0 | 87.0 | |
| | Rated output current (A) at ND | 2.5 | 4.0 | 6.0 | 7.5 | 9.5 | 13.0 | 18.0 | 26.0 | 31.0 | 37.0 | 46.0 | 61.0 | 74.0 | 90.0 | 109 | |
| | Output voltage | 0 to Mains supply voltage | | | | | | | | | | | | | | | |
| | Max. output frequency | 400 Hz | | | | | | | | | | | | | | | |
| Power supply | Rated input voltage and frequency | 3-phase 230..480 V 50/60 Hz | | | | | | | | | | | | | | | |
| | Allowable voltage fluctuation | +10%..-15% (-10% at 230V) | | | | | | | | | | | | | | | |
| | Allowable frequency fluctuation | 45 to 65 Hz | | | | | | | | | | | | | | | |

1. Based on a standard 4-pole motor for maximum applicable motor output

400 V class

| Three-phase: SX-□4□□□-E□ | | 075 | 090 | 110 | 132 | 160 | 200 | 220 | 250 | 315 | 355 | 400 | 450 | 500 | 630 | 800 | |
|---------------------------|-----------------------------------|-----------------------------|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|------|------|------|------|--|
| Motor kW | For HD setting | 55 | 75 | 90 | 110 | 132 | 160 | 200 | 220 | 250 | 315 | 355 | 400 | 450 | 500 | 630 | |
| | For ND setting | 75 | 90 | 110 | 132 | 160 | 200 | 220 | 250 | 315 | 355 | 400 | 450 | 500 | 630 | 800 | |
| Output characteristics | Max output current (A) □-EF | 175 | 210 | 252 | 300 | 360 | 450 | 516 | 600 | 720 | 780 | 900 | 1032 | 1200 | 1440 | 1800 | |
| | Max output current (A) □-EV | 175 | 210 | 252 | 300 | 360 | 450 | 516 | 600 | 720 | 780 | 900 | 1032 | 1200 | 1440 | 1800 | |
| | Rated output current (A) at HD | 117 | 140 | 168 | 200 | 240 | 300 | 344 | 400 | 480 | 520 | 600 | 688 | 800 | 960 | 1200 | |
| | Rated output current (A) at ND | 146 | 175 | 210 | 250 | 300 | 375 | 430 | 500 | 600 | 650 | 750 | 860 | 1000 | 1200 | 1500 | |
| | Output voltage | 0 to Mains supply voltage | | | | | | | | | | | | | | | |
| | Max. output frequency | 400 Hz | | | | | | | | | | | | | | | |
| Power supply | Rated input voltage and frequency | 3-phase 230..480 V 50/60 Hz | | | | | | | | | | | | | | | |
| | Allowable voltage fluctuation | +10%..-15% (-10% at 230V) | | | | | | | | | | | | | | | |
| | Allowable frequency fluctuation | 45 to 65 Hz | | | | | | | | | | | | | | | |

Specifications

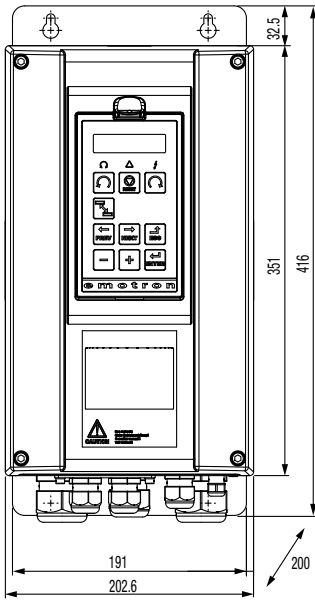
Common specifications

| Model number SX- | Specifications | |
|----------------------|---|---|
| Control functions | Control methods | V/f control for "V" type V/f control, Vector control with or without feedback for the "F" type |
| | Output frequency range | 0.0..400 Hz |
| | Frequency tolerance | Analogue set value: 1% + 1.5 LSB fsd |
| | Resolution of frequency set value | Digital set value: 0.1 Hz Analogue set value: 0.03 Hz / 60 Hz (11 bit + sign) |
| | Resolution of output frequency | 0.1 Hz |
| | Frequency set value | -10..+10 V (20 kΩ), 0..20 mA (250 Ω), frequency setting value (selectable) |
| | Starting Torque | 150% for Heavy duty, 120% for Normal duty |
| | Torque static accuracy | <3% in Vector control with feedback <3% in vector control without feedback if speed between 10 and 100%, <10% at 0 Hz |
| | Torque response | 1 ms for 0 - 90% speed 5 ms for 90 - 100% speed (Close and open loop) |
| | Speed Control Accuracy | V/f control 1% Vector control without feedback 0.1% Vector control with feedback 0.01% |
| | Speed Response | 0.4% without encoder feedback 0.2% with encoder feedback |
| | Torque Limit | From Analog input |
| | Accel/Decel Time | 0.0 to 3600.0 s |
| | Braking torque | 5 - 10% (100% with external braking resistor) |
| Functionality | Main Control Functions PID, sleep function, brake control, torque control (Direct torque control model), Pump/Fan control, Logic functions, virtual connections, overvoltage control, undervoltage override, autoreset, two motor support, Lim Switch, External trip, Preset Speeds, MotPot Up Down, Pump Feedback, Timer, Mot PreMag, Jog, Ext Mot Temp, Loc/Rem, AnIn select, Brk Ackn. | |
| Protection functions | Motor protection | Motor overheat protection based on output current or PTC by option board |
| | Momentary overcurrent Protection | Drive stops when output current exceeds 200% of peak current |
| | Overload Protection | Drive stops after 1 min at 150% of rated output current (Heavy Duty Rating) Drive stops after 1 min at 120% of rated output current (Normal Duty Rating) (1min every 10min) |
| | Overvoltage Protection | Line Overvoltage: 760 VDC during more than 10s for 400 V class; Fast Overvoltage: 850 VDC for 400 V class |
| | Undervoltage Protection | 400 VDC for 400 V class (Adjustable by input power supply parameter) |
| | Momentary power loss Ride-Thru | Low voltage override function |
| | Heatsink Overheat Protection | Protected by thermister |
| | Braking Resistance Overheat Protection | Hardware short circuit protection |
| | Stall prevention | Current limit function |
| | Power charge indication | Power LED remains lit until capacitors are charged |
| Ambient conditions | Ambient Temperature | 0°C..+40°C, up to 45°C with derating |
| | Ambient humidity | 90% RH or less (without condensation) |
| | Storage temperature | -20°C..+60°C (short-term temperature during transportation) |
| | Altitude | Up to 1000 meters (output derating of 1% per 100 m above 1000 m, max. 2000 m) |
| | Vibration / Shock | According to IEC 600068-2-6, Sinusoidal vibrations: 10<f<57 Hz, 0.075 mm, 57<f<150 Hz, 1g |
| | Contamination, according to IEC 60721-3-3 | No electrically conductive dust allowed. Cooling air must be clean and free from corrosive materials. Chemical gases, class 3C2. Solid particles, class 3S2 |
| | Protection Design | IP54 enclosure according to the EN 60529 |

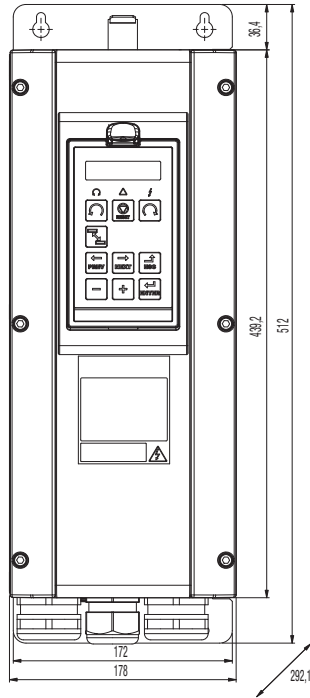
Dimensions

Standard dimensions IP54

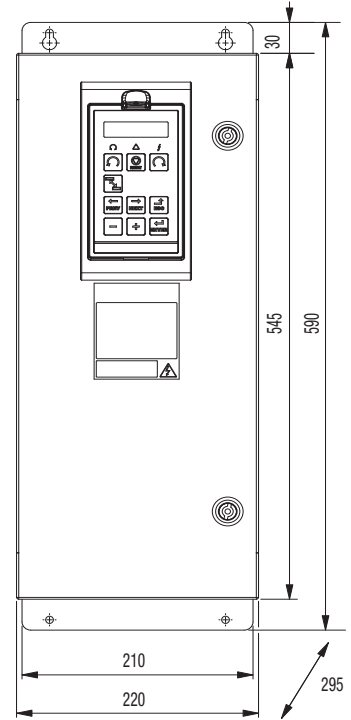
SX-D40P7 to D47P5



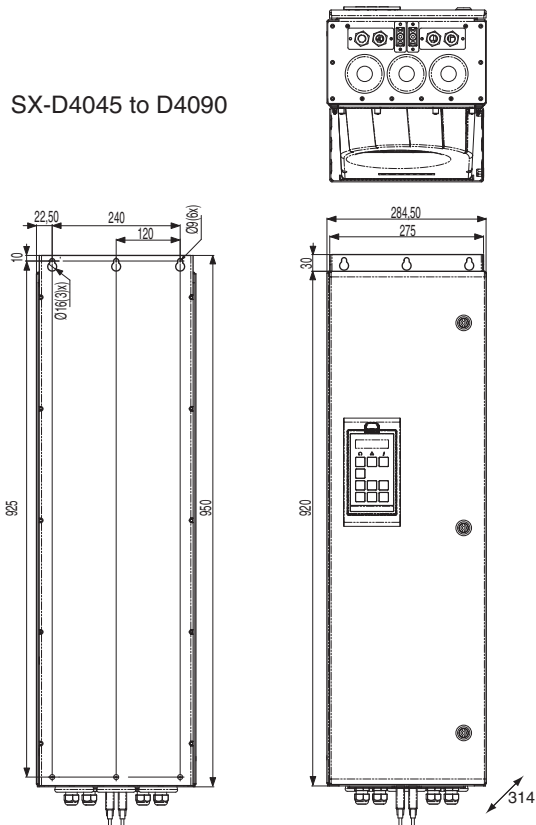
SX-D4011 to D4022



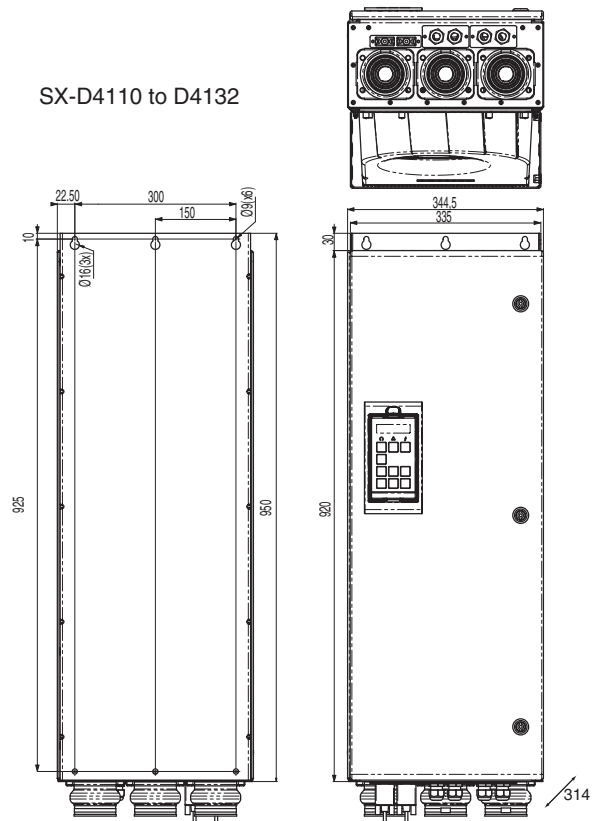
SX-D4030 to D4037

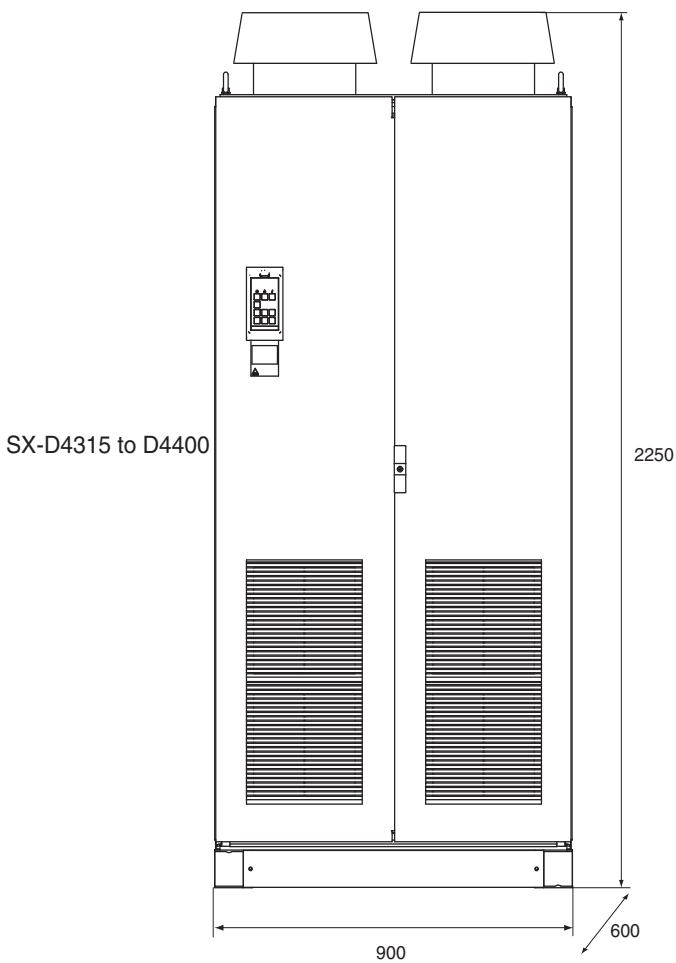
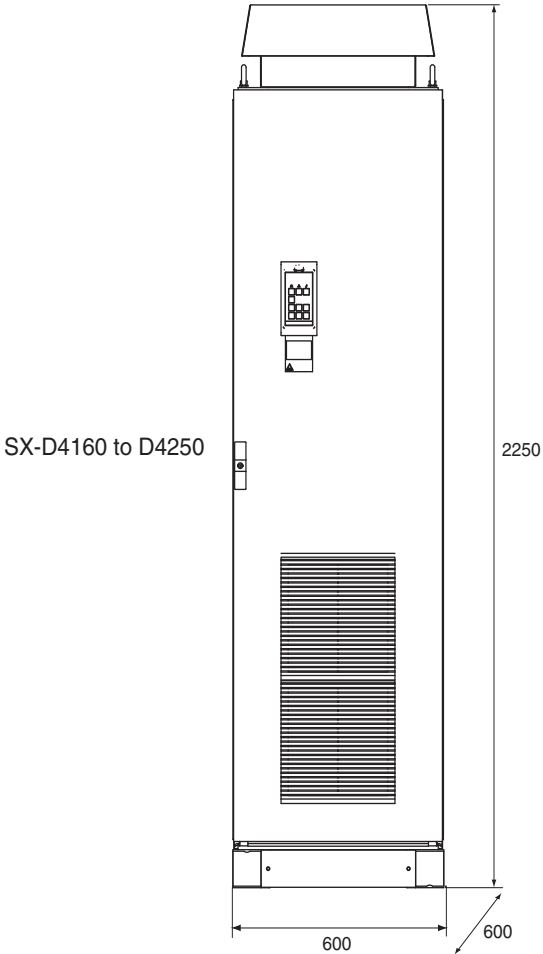


SX-D4045 to D4090

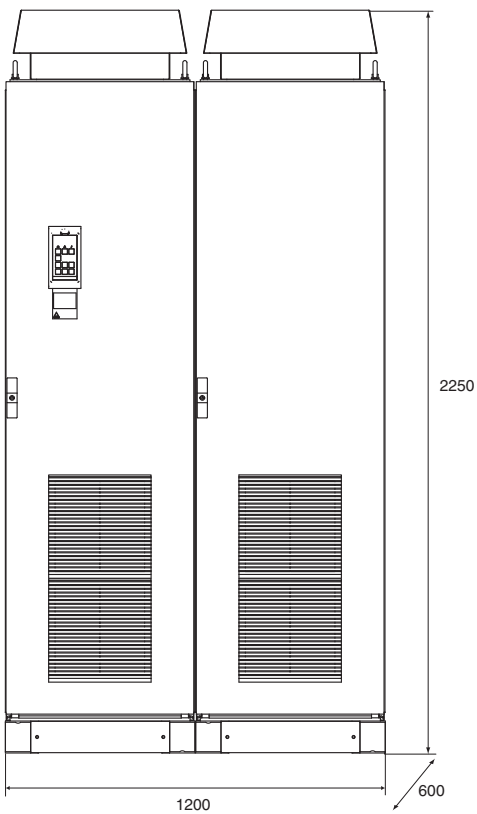


SX-D4110 to D4132

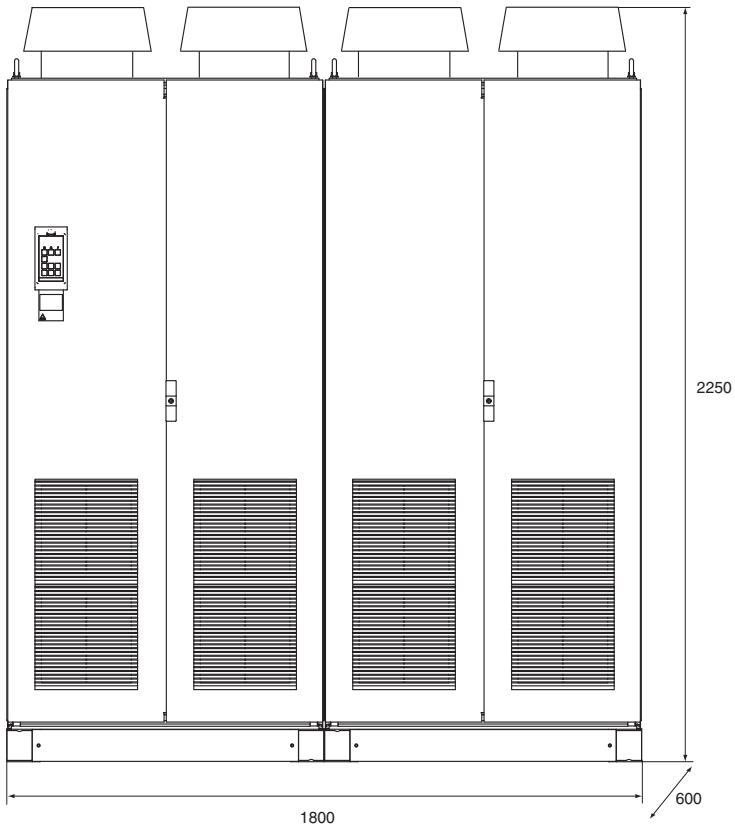




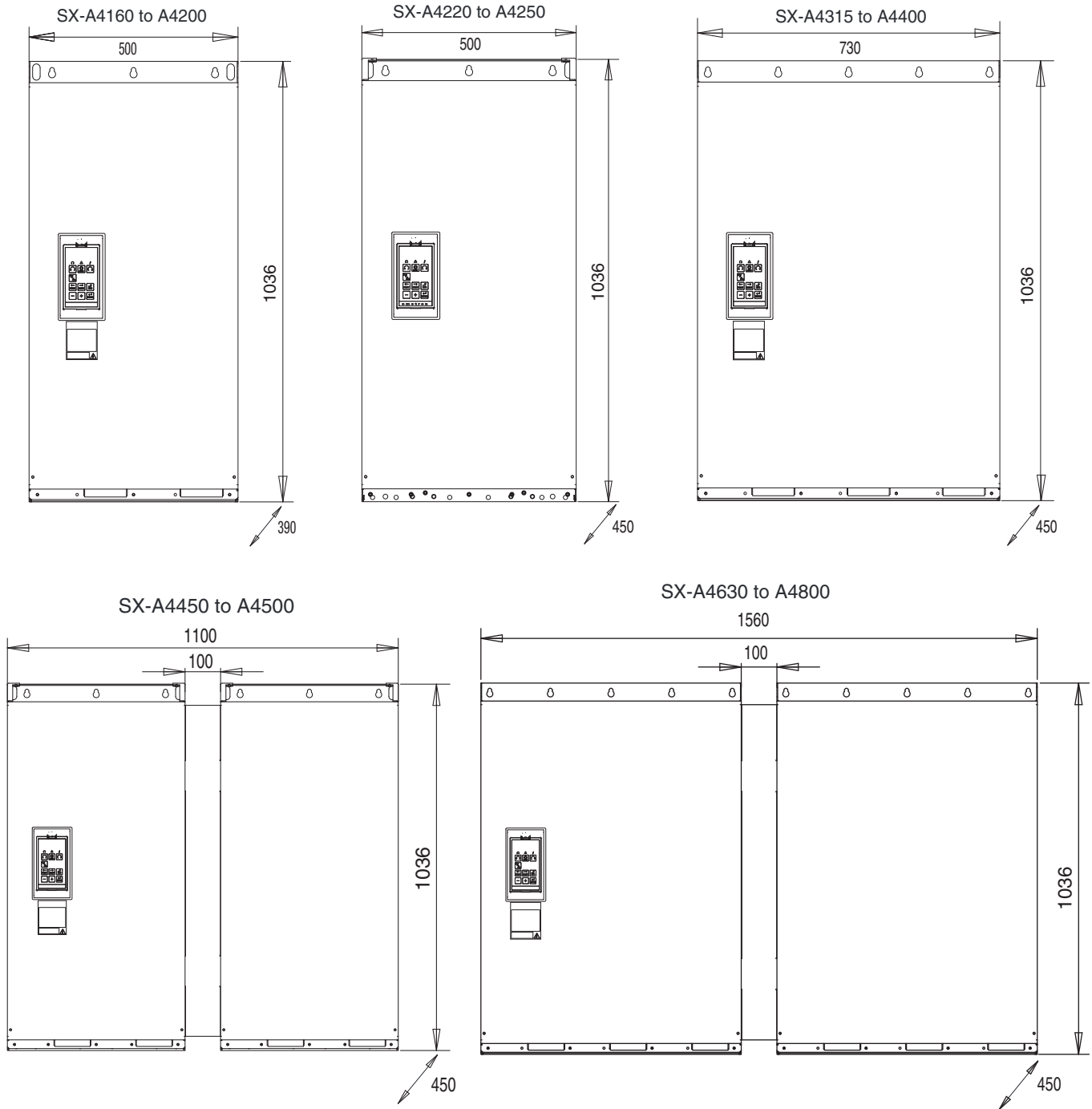
SX-D4450 to D4500



SX-D4630 to D4800



Standard dimensions IP20



Weight and Air flow

| Model SX- | Weight (Kg) | | Air flow (m ³ /hour) |
|--------------|-------------|-------------|------------------------------------|
| | SX-D (IP54) | SX-A (IP20) | |
| 0P7 to 7P5 | 12.5 | - | 75 |
| 011 to 015 | 24 | - | 120 |
| 018 to 022 | 24 | - | 170 |
| 030 to 037 | 32 | - | 175 |
| 045 to 055 | 56 | - | 510 |
| 075 to 090 | 60 | - | 510 |
| 110 to 132 | 74 | - | 800 |
| 160 to 200 | 350 | 140 | 1020 |
| 220 to 250 | 380 | 170 | 1600 |
| 315 to 400 | 506 | 248 | 2400 |
| 450 to 500 | 697 | 340 | 3200 |
| 630 to 800 | 987 | 496 | 4800 |

LCD operator



Output coils

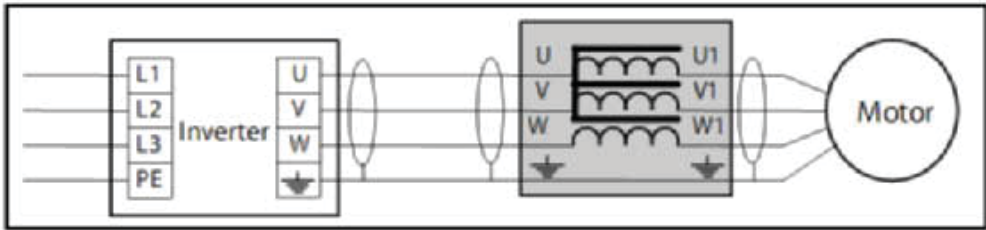
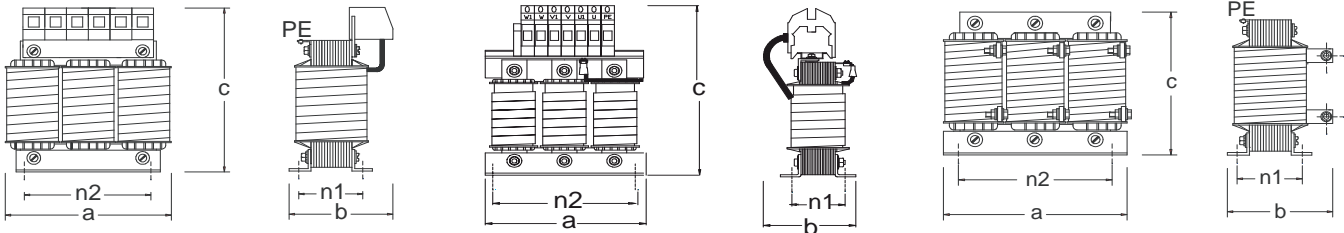


Figure 1

Figure 2

Figure 3



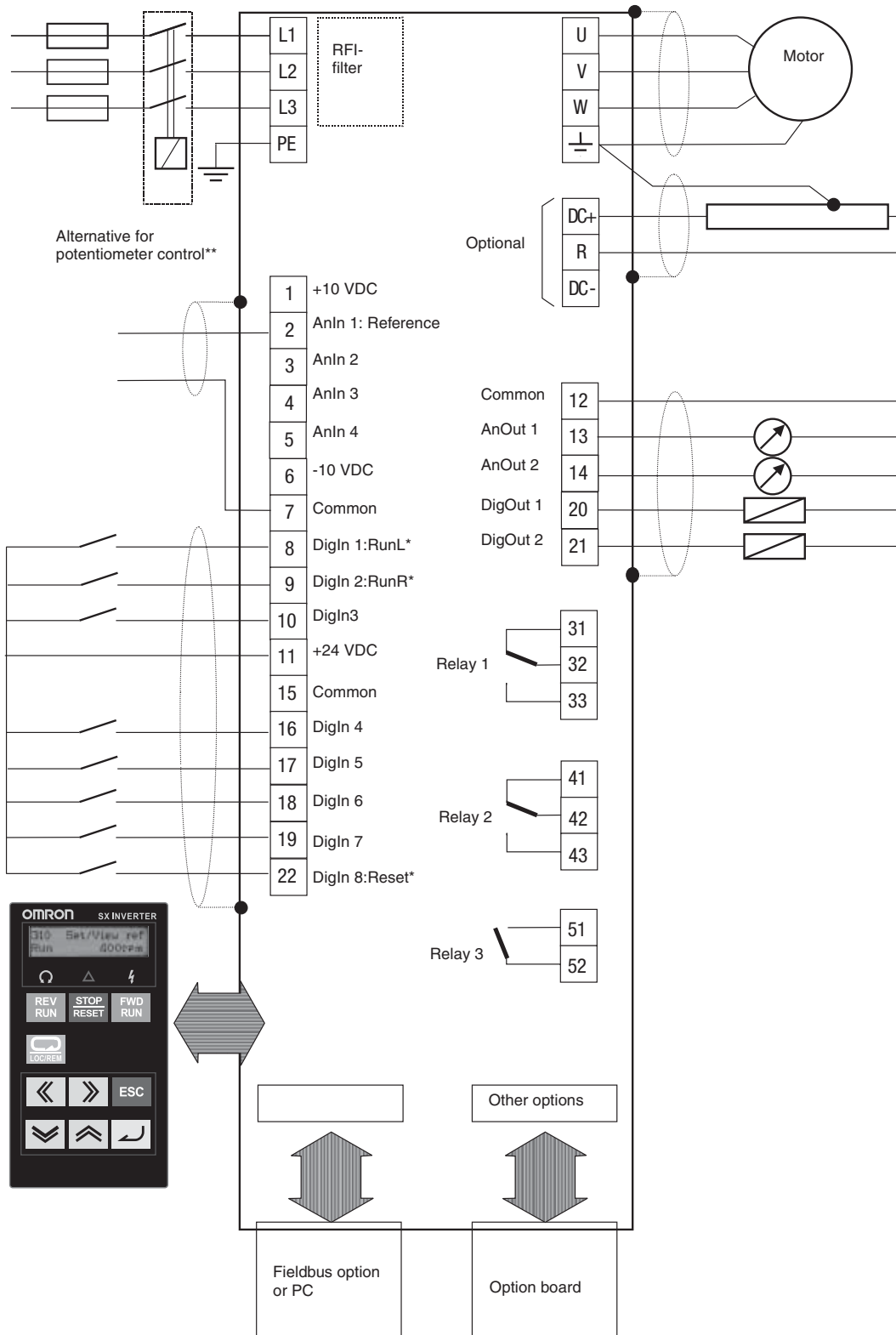
| Type | Fig | a | b | c | n2 | n1 | Fix | Weight | Connection |
|-----------|-----|-----|-----|-----|-----|----|-----|---------|---------------------|
| 473160 00 | 1 | 78 | 60 | 95 | 50 | 31 | M4 | 0.6 kg | 2.5 mm ² |
| 473161 00 | | | | | | | | | |
| 473162 00 | | | | | | | | | |
| 473163 00 | | | | | | | | | |
| 473164 00 | | | | | | | | | |
| 473165 00 | | | | | | | | | |
| 473166 00 | 2 | 96 | 74 | 105 | 71 | 48 | M4 | 1.2 kg | 4 mm ² |
| 473167 00 | | | | | | | | | |
| 473168 00 | | | | | | | | | |
| 473169 00 | 2 | 190 | 120 | 235 | 170 | 66 | M6 | 8.4 kg | 35 mm ² |
| 473170 00 | | | | | | | | | |
| 473171 00 | 3 | 210 | 160 | 180 | 175 | 97 | M6 | 13.4 kg | M10 |
| 473172 00 | | | | | | | | | |
| | | 230 | 170 | 200 | 175 | 95 | M6 | 18.4 kg | M10 |

Specifications

| Model | Rated current | Inductance | Rated voltage | Max carrier | Max output frequency | Max temp | Protection Class |
|-----------|---------------|------------|---------------|-------------|----------------------|----------|------------------|
| 473160 00 | 2.8A | 1.5 mH | 800V | 10 kHz | 200Hz | 40°C | IP00 |
| 473161 00 | 4.4A | 1.0 mH | | | | | |
| 473162 00 | 6.6A | 0.65 mH | | | | | |
| 473163 00 | 11.0A | 0.4 mH | | | | | |
| 473164 00 | 14.3A | 0.3 mH | | | | | |
| 473165 00 | 18.2A | 0.25 mH | | | | | |
| 473166 00 | 26.4A | 0.17 mH5 | | 6 kHz | 200Hz | 40°C | IP00 |
| 473167 00 | 32A | 0.15 mH | | | | | |
| 473168 00 | 65A | 0.1 mH | | | | | |
| 473169 00 | 90A | 0.1 mH | | | | | |
| 473170 00 | 146A | 0.05 mH | | | | | |
| 473171 00 | 175A | 0.05 mH | | | | | |
| 473172 00 | 275A | 0.032 mH | 1.5 kHz | 100Hz | | | |

Installation

Standard connections



NG_06-F27

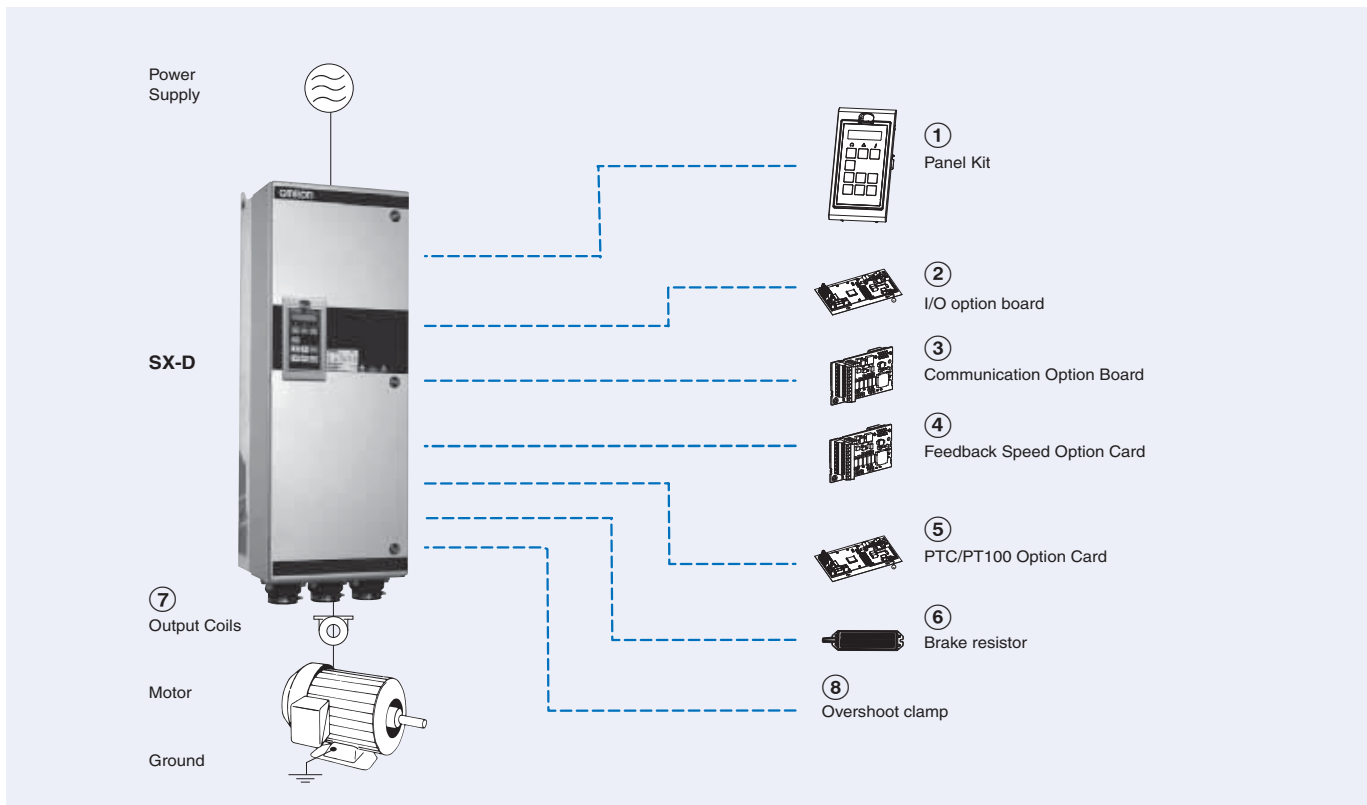
Main circuit

| Terminal | Name | Function (signal level) |
|-------------|-------------------------------------|--|
| L1, L2, L3 | Main circuit power supply input | Used to connect line power to the drive. |
| U, V, W | Inverter output | Used to connect the motor |
| DC-, DC+, R | DC link connections, Brake resistor | The brake resistor must be connected terminals DC+ and R (Terminals are only fitted if the Brake Chopper Option is built-in) |
| PE | Safety earth | Protected earth |
| | Grounding | Motor earth |

Control Circuit

| Type | No. | Signal name | Function | Signal level |
|------------------------|--------|-----------------------|---|--|
| Digital input signals | 8 | DigIn 1 | RunL (reverse) | High > 9 VDC Low < 4 VDC Max 30 VDC Impedance 4.7 kΩ for < 3.3 VDC 3.6 kΩ for > 3.3 VDC |
| | 9 | DigIn 2 | RunR (forward) | |
| | 10 | DigIn 3 | Off | |
| | 16 | DigIn 4 | Off | |
| | 17 | DigIn 5 | Off | |
| | 18 | DigIn 6 | Off | |
| | 19 | DigIn 7 | Off | |
| | 22 | DigIn 8 | RESET | |
| | 11 | +24 V | +24 VDC supply voltage | Max 100mA |
| 15 | Common | Signal ground | | |
| Analog input signals | 1 | +10 V | +10 VDC supply voltage | -10 to 10 VDC 0 to 20mA Max 30V/30mA Impedance 20 kΩ Voltage 250 Ω Current |
| | 2 | AnIn 1 | Process Ref | |
| | 3 | AnIn 2 | Off | |
| | 4 | AnIn 3 | Off | |
| | 5 | AnIn 4 | Off | |
| | 6 | -10 V | -10 VDC supply voltage | |
| | 7 | Common | Signal ground | |
| Digital output signals | 20 | DigOut 1 | Ready | High > 20VDC @ 50mA > 23VDC open Low <1 VDC @ 50mA 100 mA max together with +24VDC |
| | 21 | DigOut 2 | Brake | |
| | 12 | Common | Signal ground | |
| | 31 | N/C 1 | Relay 1 output Trip, active when the VSD is in a TRIP condition. | 0.1 to 2A 250 VAC or 42 VDC |
| | 32 | COM 1 | | |
| | 33 | N/O 1 | | |
| | 41 | N/C 2 | Relay 2 output Run, active when the VSD is started. | |
| | 42 | COM 2 | | |
| | 43 | N/O 2 | | |
| 51 | COM 3 | Relay 3 output Off | | |
| 52 | N/O 3 | | | |
| Analog output signals | 12 | Common | Signal ground | |
| | 13 | AnOut1 | Min speed to max speed | |
| | 14 | AnOut2 | 0 to max torque | |

Ordering information



SX

| Specifications | | | | | IP54 Model | | IP20 Model | |
|----------------|------------|--------|-------------|-------------|-----------------------|-------------|-----------------------|-------------|
| Voltage | Heavy Duty | | Normal Duty | | Direct torque control | V/F | Direct torque control | V/F |
| 400 V | 0.55 kW | 2.0 A | 0.75 kW | 2.5 A | SX-D40P7-EF | SX-D40P7-EV | | |
| | 1.1 kW | 3.2 A | 1.5 kW | 4.0 A | SX-D41P5-EF | SX-D41P5-EV | | |
| | 1.5 kW | 4.8 A | 2.2 kW | 6.0 A | SX-D42P2-EF | SX-D42P2-EV | | |
| | 2.2 kW | 6.0 A | 3 kW | 7.5 A | SX-D43P0-EF | SX-D43P0-EV | | |
| | 3 kW | 7.6 A | 4 kW | 9.5 A | SX-D44P0-EF | SX-D44P0-EV | | |
| | 4 kW | 10.4 A | 5.5 kW | 13 A | SX-D45P5-EF | SX-D45P5-EV | | |
| | 5.5 kW | 14.4 A | 7.5 kW | 18 A | SX-D47P5-EF | SX-D47P5-EV | | |
| | 7.5 kW | 21 A | 11 kW | 26 A | SX-D4011-EF | SX-D4011-EV | | |
| | 11 kW | 25 A | 15 kW | 31 A | SX-D4015-EF | SX-D4015-EV | | |
| | 15 kW | 29.6 A | 18.5 kW | 37 A | SX-D4018-EF | SX-D4018-EV | | |
| | 18.5 kW | 37 A | 22 kW | 46 A | SX-D4022-EF | SX-D4022-EV | | |
| | 22 kW | 49 A | 30 kW | 61 A | SX-D4030-EF | SX-D4030-EV | | |
| | 30 kW | 59 A | 37 kW | 74 A | SX-D4037-EF | SX-D4037-EV | | |
| | 37 kW | 72 A | 45 kW | 90 A | SX-D4045-EF | SX-D4045-EV | | |
| | 45 kW | 87 A | 55 kW | 109 A | SX-D4055-EF | SX-D4055-EV | | |
| | 55 kW | 117 A | 75 kW | 146 A | SX-D4075-EF | SX-D4075-EV | | |
| | 75 kW | 140 A | 90 kW | 175 A | SX-D4090-EF | SX-D4090-EV | | |
| | 90 kW | 168 A | 110 kW | 210 A | SX-D4110-EF | SX-D4110-EV | | |
| | 110 kW | 200 A | 132 kW | 250 A | SX-D4132-EF | SX-D4132-EV | | |
| | 132 kW | 240 A | 160 kW | 300 A | SX-D4160-EF | SX-D4160-EV | SX-A4160-EF | SX-A4160-EV |
| | 160 kW | 300 A | 200 kW | 375 A | SX-D4200-EF | SX-D4200-EV | SX-A4200-EF | SX-A4200-EV |
| | 200 kW | 344 A | 220 kW | 430 A | SX-D4220-EF | SX-D4220-EV | SX-A4220-EF | SX-A4220-EV |
| | 220 kW | 400 A | 250 kW | 500 A | SX-D4250-EF | SX-D4250-EV | SX-A4250-EF | SX-A4250-EV |
| | 250 kW | 480 A | 315 kW | 600 A | SX-D4315-EF | SX-D4315-EV | SX-A4315-EF | SX-A4315-EV |
| | 315 kW | 520 A | 355 kW | 650 A | SX-D4355-EF | SX-D4355-EV | SX-A4355-EF | SX-A4355-EV |
| | 355 kW | 600 A | 400 kW | 750 A | SX-D4400-EF | SX-D4400-EV | SX-A4400-EF | SX-A4400-EV |
| | 400 kW | 688 A | 450 kW | 680 A | SX-D4450-EF | SX-D4450-EV | SX-A4450-EF | SX-A4450-EV |
| | 450 kW | 800 A | 500 kW | 1000 A | SX-D4500-EF | SX-D4500-EV | SX-A4500-EF | SX-A4500-EV |
| 500 kW | 960 A | 630 kW | 1200 A | SX-D4630-EF | SX-D4630-EV | SX-A4630-EF | SX-A4630-EV | |
| 630 kW | 1200 A | 800 kW | 1500 A | SX-D4800-EF | SX-D4800-EV | SX-A4800-EF | SX-A4800-EV | |

① Panel Kit

| Model | Description | Function |
|------------|-----------------|--|
| 01-3957-00 | Panel kit | Panel kit complete including panel |
| 01-3957-01 | Blank panel kit | Panel kit complete including blank panel |

② I/O option board

| Model | Description | Function |
|------------|-----------------------|--|
| 01-3876-01 | Additional I/O option | Provides 3 extra relay outputs and 3 additional digital inputs |
| 01-3876-07 | Crane option | Dedicated option board for crane application, including additional I/O and functions |

③ Communication option board

| Type | Model | Description | Function |
|----------------------------|------------|-------------------------|---|
| Communication option board | 01-3876-04 | RS232/485 | • MODBUS RTU serial communication by RS232 or RS485 interface with galvanic isolation |
| | 01-3876-05 | PROFIBUS-DP option card | • Used for operating the inverter through PROFIBUS-DP communication with the host controller. |
| | 01-3876-06 | DeviceNet option card | • Used for operating the inverter through DeviceNet communication with the host controller. |
| | 01-3876-09 | Modbus/TCP, Ethernet | • Used for operating the inverter through Modbus/TCP communication with the host controller. |

④ Encoder feedback option card

| Model | Description | Function |
|------------|----------------|---|
| 01-3876-03 | Encoder option | Used for connection of the actual motor speed via encoder. Up to 100kHz with TTL and HTL incremental encoders with 5/24 V power supply |

⑤ PTC/PT100 option card

| Model | Description | Function |
|------------|--------------------|--|
| 01-3876-08 | Thermal protection | Allows to connect a motor thermistor to the inverter |

⑥ Braking chopper and braking resistor

All inverter sizes could be fitted with an optional built-in brake chopper from factory but is not possible to install it later. The choice of the resistor depends on the application switch-on duration and duty-cycle. Following tables describes the activation level of the built-in braking chopper and the minimum resistor that could be used depending on the input voltage.

| Type | R for different input voltage (Ω) | | | Type | R for different input voltage (Ω) | | |
|---------|-----------------------------------|-------------|-------------|---------|-----------------------------------|-------------|-------------|
| | 220-240 VAC | 380-415 VAC | 440-480 VAC | | 220-240 VAC | 380-415 VAC | 440-480 VAC |
| SX-40P7 | 43 | 43 | 50 | SX-4075 | 3.8 | 3.8 | 4.4 |
| SX-41P5 | 43 | 43 | 50 | SX-4090 | 3.8 | 3.8 | 4.4 |
| SX-42P2 | 43 | 43 | 50 | SX-4110 | 2.7 | 2.7 | 3.1 |
| SX-43P0 | 43 | 43 | 50 | SX-4132 | 2.7 | 2.7 | 3.1 |
| SX-44P0 | 43 | 43 | 50 | SX-4160 | 2 x 3.8 | 2 x 3.8 | 2 x 4.4 |
| SX-45P5 | 43 | 43 | 50 | SX-4200 | 2 x 3.8 | 2 x 3.8 | 2 x 4.4 |
| SX-47P5 | 43 | 43 | 50 | SX-4220 | 2 x 2.7 | 2 x 2.7 | 2 x 3.1 |
| SX-4011 | 26 | 26 | 30 | SX-4250 | 2 x 2.7 | 2 x 2.7 | 2 x 3.1 |
| SX-4015 | 26 | 26 | 30 | SX-4315 | 3 x 2.7 | 3 x 2.7 | 3 x 3.1 |
| SX-4018 | 17 | 17 | 20 | SX-4355 | 3 x 2.7 | 3 x 2.7 | 3 x 3.1 |
| SX-4022 | 17 | 17 | 20 | SX-4400 | 3 x 2.7 | 3 x 2.7 | 3 x 3.1 |
| SX-4030 | 9.7 | 9.7 | N/A | SX-4450 | 4 x 2.7 | 4 x 2.7 | 4 x 3.1 |
| SX-4037 | 9.7 | 9.7 | N/A | SX-4500 | 4 x 2.7 | 4 x 2.7 | 4 x 3.1 |
| SX-4045 | 3.8 | 3.8 | 4.4 | SX-4630 | 6 x 2.7 | 6 x 2.7 | 6 x 3.1 |
| SX-4055 | 3.8 | 3.8 | 4.4 | | - | - | - |

| Supply voltage (VAC) | Built-in brake chopper trigger level (VDC) |
|----------------------|--|
| 220-240 | 380 |
| 380-415 | 660 |
| 440-480 | 780 |

⑦ Output coils

Output coils above SX-D4132-E should be order from factory as they should be installed inside of the cabinet

| Voltage | Inverter model | Model | Rated current | Inductance | Rated Voltage | Max carrier | Max output frequency | Max temp |
|-----------|----------------|-----------|---------------|------------|---------------|-------------|----------------------|----------|
| 400V | SX-40P7-E | 473160 00 | 2.8A | 1.5 mH | 800V | 10 KHz | 200 | 40°C |
| | SX-41P5-E | 473161 00 | 4.4A | 1.0 mH | | | | |
| | SX-42P2-E | 473162 00 | 6.6A | 0.65 mH | | | | |
| | SX-43P0-E | 473163 00 | 11.0A | 0.4 mH | | | | |
| | SX-44P0-E | | | | | | | |
| | SX-45P5-E | 473164 00 | 14.3A | 0.3 mH | | | | |
| | SX-47P5-E | 473165 00 | 18.2A | 0.25 mH | | | | |
| | SX-4011-E | 473166 00 | 26.4A | 0.175 mH | | | | |
| | SX-4015-E | 473167 00 | 32A | 0.15 mH | | | | |
| | SX-4018-E | 473168 00 | 65A | 0.1 mH | | | | |
| | SX-4022-E | | | | | | | |
| | SX-4030-E | | | | | | | |
| | SX-4037-E | 473169 00 | 90A | 0.1 mH | | | | |
| | SX-4045-E | | | | | | | |
| | SX-4055-E | 473170 00 | 146A | 0.05 mH | | | | |
| | SX-4075-E | | | | | | | |
| | SX-4090-E | 473171 00 | 175A | 0.05 mH | | | | |
| SX-4110-E | 473172 00 | 275A | 0.032 mH | | | | | |
| SX-4132-E | | | | | | | | |
| | | | | | | 6 KHz | | |
| | | | | | | 1.5 KHz | 100 | |

⑧ Overshoot clamp

Only two types of overshoot clamps could be order for after mounting

| Model | Inverter | Function |
|-------|--------------------|--|
| 52163 | SX-40P7 to SX-4132 | Together with the output coils, the overshoot clamp restricts the voltage and the dV/dt on the motor winding. Inverters must be ordered including the option DC+/DC- connectors. |
| 52220 | SX-4160 to SX-4800 | Together with the output coils, the overshoot clamp restricts the voltage and the dV/dt on the motor winding. Doesn't require the "DC+/DC-" option. |

Computer software

| Types | Model | Description | Installation |
|----------|----------|-------------------|---|
| Software | CX-drive | Computer software | Configuration and monitoring software tool |
| | CX-One | Computer software | Configuration and monitoring software tool |
| | €Saver | Computer software | Software tool for Energy Saving calculation |

ALL DIMENSIONS SHOWN ARE IN MILLIMETERS.
To convert millimeters into inches, multiply by 0.03937. To convert grams into ounces, multiply by 0.03527.